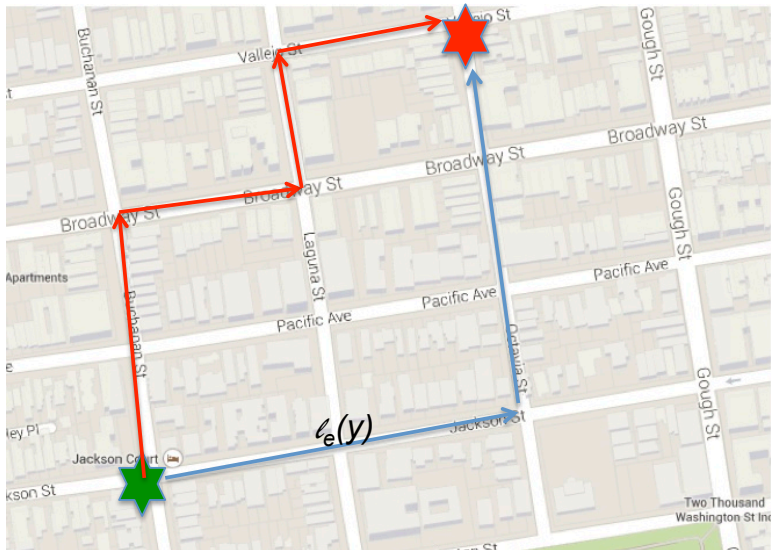


*Mechanism Design in Large Congestion Games*

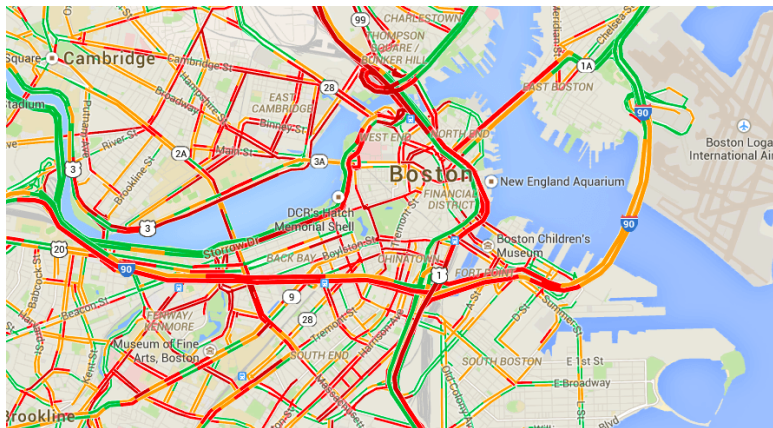
**Ryan Rogers**, Aaron Roth, Jonathan Ullman, and Steven Wu

July 22, 2015

# Routing Game



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  - A set of actions  $A \implies$  **routes** for each source destination pair.
  - A **cost function**  $c : \mathcal{T} \times A^n \rightarrow \mathbb{R}$  depends on **congestion**  $y_e$  on each edge

$$c(t_i, \mathbf{a}) = \sum_{e \in a_i} \ell_e(y_e(\mathbf{a})).$$

## *Incomplete Information Setting*



*Players may not know each other's  
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*Players may not know each other's type - **incomplete information**.*

- *Sources and destinations may be sensitive information,*
- *n may be HUGE!!*

## *First Goal - Equilibrium Selection*

### *Definition*

An action profile  $\mathbf{a} = (a_1, \dots, a_n)$  is an  $\eta$ -Nash equilibrium if for every player  $i$  of type  $t_i \in \mathcal{T}$  and every deviation  $a'_i$  we have

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Finding a NE requires knowing the types of every player

- **Goal 1:** Coordinate players to play an approximate Nash equilibrium *as if we knew the types*, even in settings of incomplete information.

## Second Goal - Social Welfare

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An action profile  $\mathbf{a}$  is an  $\eta$ -Socially Optimal Routing if

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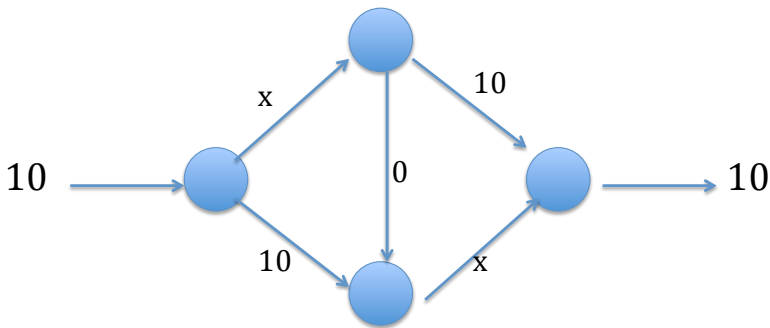
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- **Goal 2:** Coordinate selfish players to play an approximate social optimal routing *as if we knew the types*, in settings of incomplete information.

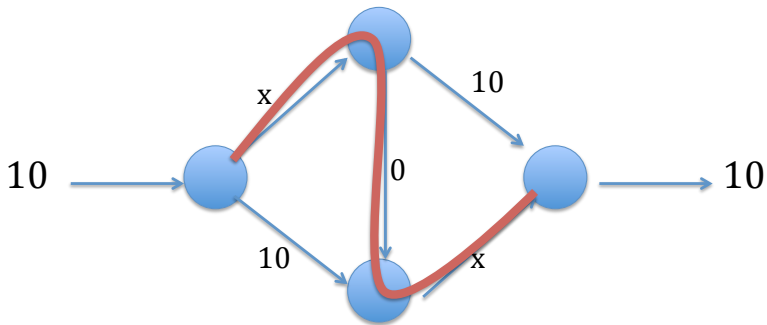
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Is it true that the Social Optimal is a NE?



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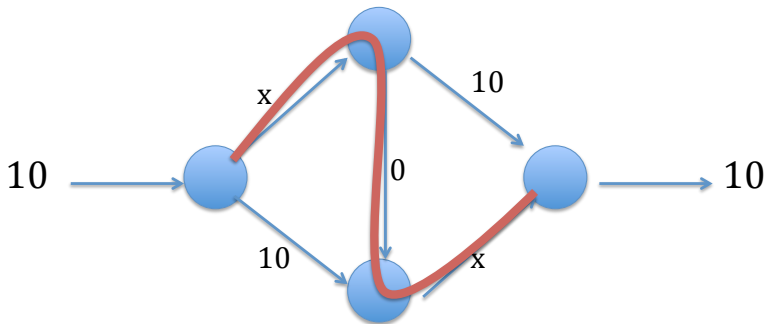
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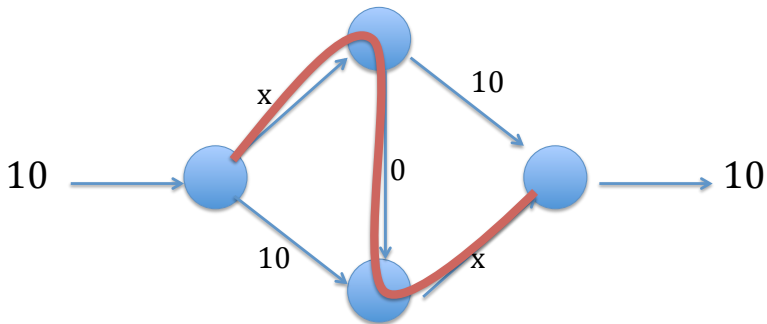
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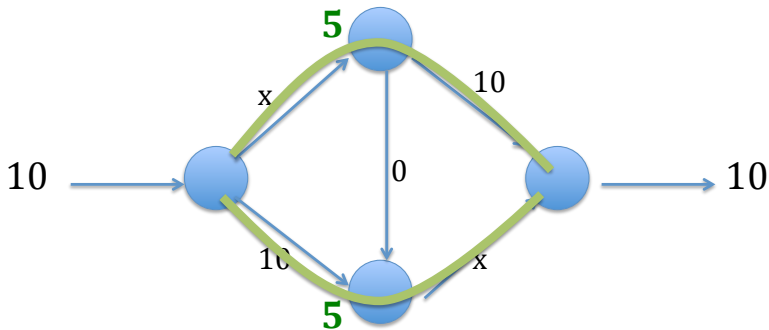


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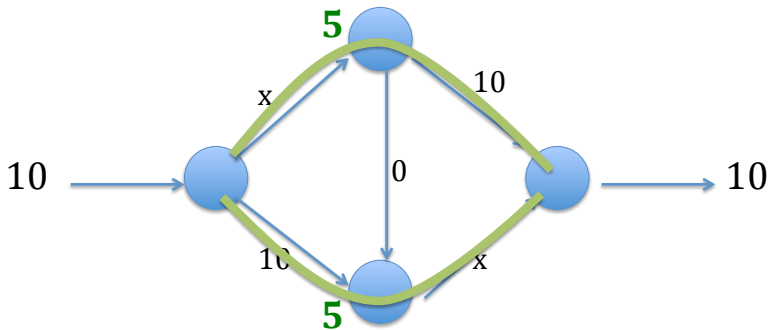
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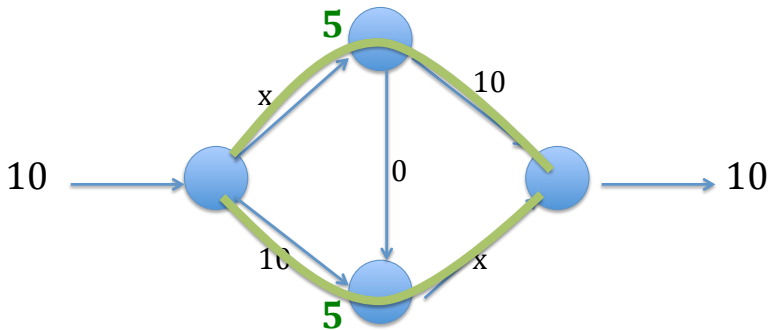
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## *Goal One: Equilibrium Selection*

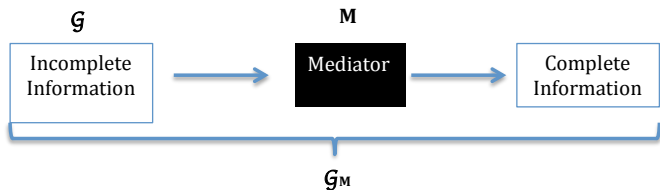
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- Mediator for a Routing Game:

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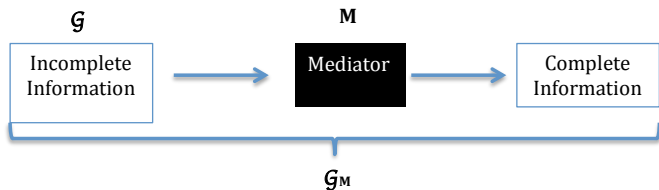


## Mediated Game



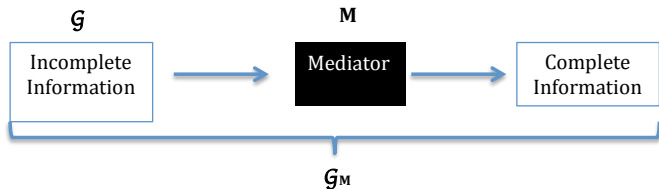
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- Players' actions include how they will interact with  $M$ .

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## *Weak Mediator*

- *Mediator cannot force people to use it.*
- *Players need not follow its suggested action.*
- *Players may lie to the mediator if they choose to use it.*





## *Good Behavior*



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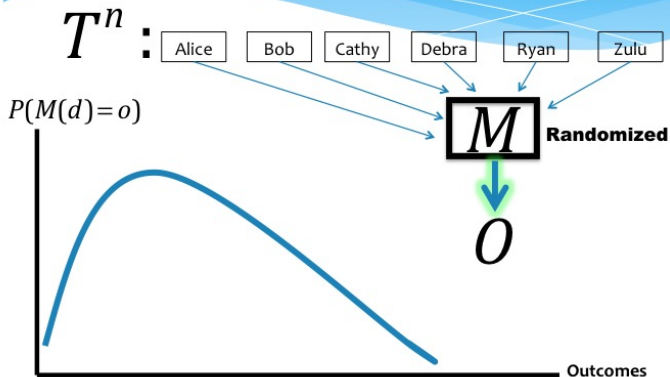
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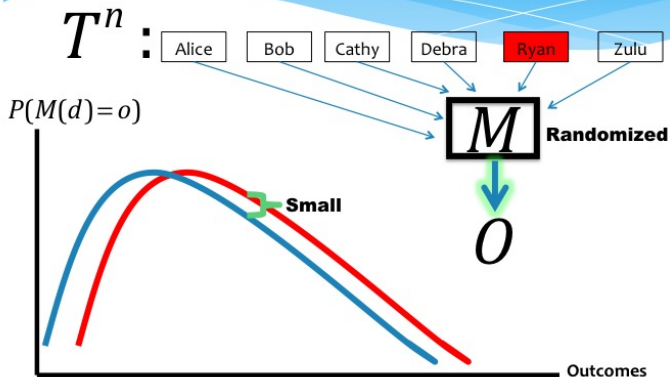
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- If all players report truthfully, then there is little incentive to not follow  $M$ 's suggestion.
- If one person changes her type, the game has changed and the NE may be very different - costs to players may be very different between different NE.
- How do we control the impact any one player has on the outcome of  $M$ ?



# Differential Privacy [DMNS'06]



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## *Differential Privacy [DMNS'06]*

### *Definition*

A randomized algorithm  $M : \mathcal{T}^n \rightarrow \mathcal{O}$  is  $\epsilon$ -DP if for all neighboring datasets  $\mathbf{t}$  and  $\mathbf{t}'$  and all outcome sets  $B \subseteq \mathcal{O}$  we have

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Too strong of a definition in our case. We want player's actions to depend on their reported type.

## Relaxation of DP - Joint DP [KPRU'14]

### Definition

A randomized algorithm  $M : \mathcal{T}^n \rightarrow A^n$  is  $\epsilon$ -JDP if for every player  $i$ ,  $\mathbf{t}_{-i} \in \mathcal{T}^{n-1}$ ,  $t_i, t'_i \in \mathcal{T}$ , and all outcome sets  $B \subseteq A^{n-1}$ ,

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Allows outcome for player  $i$  to depend on  $i$ 's report  $t_i$ .

## *JDP Mediators*

**Key Property:** A JDP mediator that also computes an equilibrium of the underlying game is approximately truthful.



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### *Theorem*

Let  $\mathcal{G}$  be **any** game with costs in  $[0, m]$ , and let  $M$  be a mediator such that

- It is  $\epsilon$ -JDP
- For any set of reported types  $\mathbf{t}$ , it outputs an  $\eta$ -approximate pure strategy Nash Equilibrium.

Then **good behavior** is an  $\eta'$ -**approximate ex-post Nash Equilibrium** for the incomplete information game  $\mathcal{G}_M$  where

$$\eta' = 2m\epsilon + \eta$$

## *Main Result for Equilibrium Selection*

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Resulting play of good behavior is an  $\eta'$  approximate NE of the complete information game.

## *Large Games*



## Large Games

- We assume that each player cannot significantly change the cost of another player by changing her route.

$$|\ell_e(y_e) - \ell_e(y_e + 1)| \leq \frac{1}{n} \quad \text{for } y_e \in [n] \text{ and } e \in E.$$

- The costs then satisfy for  $j \neq i$  and  $a_j \neq a'_j \in A$

$$|c(t_i, (a_j, \mathbf{a}_{-j})) - c(t_i, (a'_j, \mathbf{a}_{-j}))| \leq \frac{m}{n}.$$

## *How to Construct Such a Mechanism?*



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- Simulate Best Response Dynamics  $\implies$  obtains a NE in routing games [MS'96].
- Compute Best Responses privately  $\implies$  costs only depend on the number of people on each edge.
- Limit the number of times a single player can change routes  $\implies$  uses the “largeness” assumption.

## Billboard Lemma



- If a mechanism  $M : \mathcal{T}^n \rightarrow \mathcal{O}$  is  $(\epsilon, \delta)$ -DP and consider any function  $\phi : \mathcal{T} \times \mathcal{O} \rightarrow \mathcal{A}$ . Define  $M' : \mathcal{T}^n \rightarrow \mathcal{A}^n$  to be

$$M'(\mathbf{t})_i = \phi(t_i, M(\mathbf{t})).$$

Then  $M'$  is  $(\epsilon, \delta)$ -JDP.

## Goal Two - Social Welfare

Recall that we want to minimize the cost to all players:

### *Definition*

An action profile  $\mathbf{a}$  is an  $\eta$ -Socially Optimal Routing if

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How to get selfish agents to play the socially optimal routing without knowing their types?

## Classical Approach - Tolls

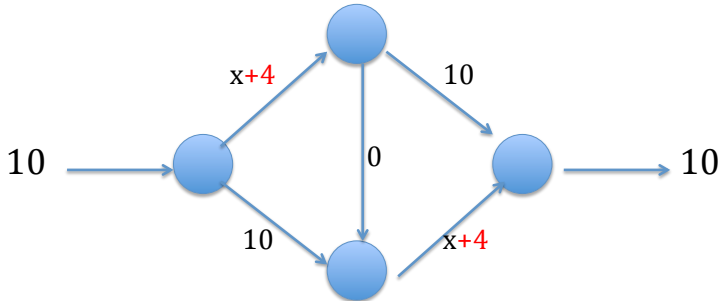


Add constant *tolls*  $\tau = (\tau_e)_{e \in E}$  to the edges such that a NE of the game with tolls (*toll*ed game) is the socially optimal in the game without tolls. However these tolls depend on players' types.

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## *Modified Mediator for Social Welfare*

- Mediator still **suggests routes** to each player  $\mathbf{a} = (a_1, \dots, a_n)$  that they may or may not follow, but it also outputs **tolls**  $\tau = (\tau_e)_{e \in E}$  on each edge, that every player must pay.
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## *JDP Mediators + Tolls*

Recall:  $JDP + NE \implies \text{truthfulness}$

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### *Theorem*

Let  $M_i : (\mathcal{T} \cup \perp) \rightarrow A \times [0, U]^m$  where  $M_i(\mathbf{t}) = (M_i^A(\mathbf{t}), M_i^T(\mathbf{t}))$  outputs a suggested route and tolls for each edge. If

$M = (M_1, \dots, M_n)$  satisfies both

- $\epsilon$ -JDP and
- for any input types  $\mathbf{t}$ , the action profile  $\mathbf{a} = M^A(\mathbf{t})$  is an  $\eta$ -approximate NE in the modified routing game with

$$\ell_e^M(\mathbf{y}) = \ell_e(\mathbf{y}) + M_e^T(\mathbf{t})$$

then **good behavior** is an  $\eta'$  approximate ex-post NE in the mediated tolled game, where

$$\eta' = \eta + 2m(U + 1)\epsilon$$

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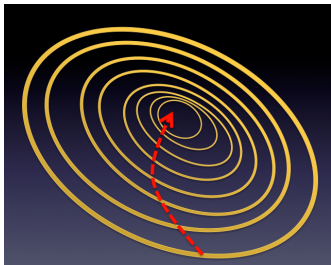
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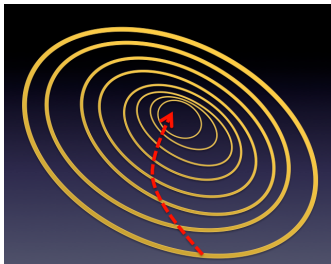
- Resulting play of good behavior is an  $\tilde{O}(mn^{4/5})$  socially optimal routing.
- As long as the optimal solution grows  $\omega(n^{4/5})$ , then we get a  $(1 + o(1))$  multiplicative approximation to the true optimal.

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- Compute an approximately optimal flow  $\mathbf{a}^\bullet$  subject to JDP via a privacy preserving projected **gradient descent** algorithm.

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- Given target flow  $\mathbf{a}^\bullet$ , we find the necessary tolls  $\hat{\tau}$  so that **most** players are **nearly** best responding in this tolled game when playing  $\mathbf{a}^\bullet$ .



## *How to Construct such a Mediator*

- Allow the **few** players that are not approximately best responding to then best respond in the tolled game. This will modify  $\mathbf{a}^\bullet$  only slightly (by **largeness** assumption) and so will remain nearly optimal in the original game.

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- Allow the **few** players that are not approximately best responding to then best respond in the tolled game. This will modify  $\mathbf{a}^*$  only slightly (by **largeness** assumption) and so will remain nearly optimal in the original game.
- Resulting flow  $\hat{\mathbf{a}}$  is then nearly optimal in the **original game** and an approximate NE in the **tolled game** with tolls  $\hat{\tau}$ .



## *Recap*

Key Property:  $NE + JDP \implies$  Approx Truthful Mediator

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#### Main Result:

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### Social Welfare Mediator

#### Main Result:

*Output routing within  $(1 + \tilde{o}(1))$  OPT*



QUESTIONS?