

Field Axioms. A *field* is a set \mathbb{F} along with two operations, “addition” and “multiplication,” that obey the following six axioms:

- F-I) (Commutativity) If $x, y \in \mathbb{F}$ then $xy = yx$ and $x + y = y + x$.
- F-II) (Associativity) If $x, y, z \in \mathbb{F}$ then $x(yz) = (xy)z$ and $x + (y + z) = (x + y) + z$.
- F-III) (Distributivity) If $x, y, z \in \mathbb{F}$ then $x(y + z) = xy + xz$.
- F-IV) (Identity) There exist two distinct elements $0, 1 \in \mathbb{F}$ (the additive identity and the multiplicative identity, respectively) so that for any $x \in \mathbb{F}$, we have $0 + x = x$ and $1x = x$.
- F-V) (Additive Inverses) Given any $x \in \mathbb{F}$, there is some $y \in \mathbb{F}$ (commonly denoted $-x$) so that $x + y = 0$.
- F-VI) (Multiplicative Inverses) Given any $x \in \mathbb{F}$ except $x = 0$, there is some $y \in \mathbb{F}$ (commonly denoted x^{-1}) so that $xy = 1$.

Order Axioms. A field F is called an *ordered field* if there is some subset $\mathbb{F}^+ \subset \mathbb{F}$ (called the “positive” elements of \mathbb{F}) so that the following three axioms hold:

- O-I) If $x, y \in \mathbb{F}^+$ then $x + y \in \mathbb{F}^+$ and $xy \in \mathbb{F}^+$.
- O-II) If $x \in \mathbb{F}$ and $x \neq 0$, then either $x \in \mathbb{F}^+$ or $-x \in \mathbb{F}^+$, but not both.
- O-III) $0 \notin \mathbb{F}^+$.

Completeness. An ordered field \mathbb{F} is called *complete* if

- C-I) Every subset of \mathbb{F} that has an upper bound has a least upper bound.

Theorem. There is a unique complete ordered field, which is the real numbers.

Properties of Integration

a) (Additivity of the Interval.) If $a < b < c$ and $f(x)$ is integrable on $[a, c]$ then

$$\int_a^b f(x) dx + \int_b^c f(x) dx = \int_a^c f(x) dx.$$

b) (Translation Invariance.) If $f(x)$ is integrable on $[a, b]$ and $c \in \mathbb{R}$ then

$$\int_a^b f(x) dx = \int_{a+c}^{b+c} f(x-c) dx.$$

c) (Scale Invariance.) If $f(x)$ is integrable on $[a, b]$ and $k \in \mathbb{R}$, $k \neq 0$, then

$$\int_a^b f(x) dx = \frac{1}{k} \int_{ka}^{kb} f\left(\frac{x}{k}\right) dx.$$

d) (Linearity.) If $f(x), g(x)$ are integrable on $[a, b]$ and c_1, c_2 are constants, then

$$\int_a^b (c_1 f(x) + c_2 g(x)) dx = c_1 \int_a^b f(x) dx + c_2 \int_a^b g(x) dx$$

e) (Comparison.) If $g(x) \leq f(x)$ and both are integrable on $[a, b]$, then

$$\int_a^b g(x) dx \leq \int_a^b f(x) dx.$$

f) (Triangle Inequality.) If $f(x)$ is integrable on $[a, b]$, then

$$\left| \int_a^b f(x) dx \right| \leq \int_a^b |f(x)| dx$$

If $\vec{f}(t)$ is an integrable vector-valued function, then $\|\vec{f}(t)\|$ is integrable and

$$\left\| \int_a^b \vec{f}(x) dx \right\| \leq \int_a^b \|\vec{f}(x)\| dx$$

g) (Integrability of Step Functions.) If $g(x)$ is the step function subordinate to the partition $P = \{x_0, x_1, \dots, x_N\}$ of $[a, b]$ which takes on the value g_k on the interior of the k^{th} interval, then $g(x)$ is integrable on $[a, b]$ and

$$\int_a^b g(x) dx = \sum_{k=1}^N g_k \cdot (x_k - x_{k-1}).$$

(Note that constant functions are step functions.)

Properties of the Bilinear Dot Product.

- a) (Positivity) If $\vec{A} \in \mathbb{R}^n$ then $\vec{A} \cdot \vec{A} \geq 0$, with equality if and only if $\vec{A} = \mathcal{O}$
- b) (Symmetry) If $\vec{A}, \vec{B} \in \mathbb{R}^n$ then $\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$
- c) (Bilinearity) If $\vec{A}, \vec{B}, \vec{A}_1, \vec{A}_2, \vec{B}_1, \vec{B}_2 \in \mathbb{R}^n$ and $c_1, c_2 \in \mathbb{R}$ then

$$\begin{aligned}(c_1\vec{A}_1 + c_2\vec{A}_2) \cdot \vec{B} &= c_1(\vec{A}_1 \cdot \vec{B}) + c_2(\vec{A}_2 \cdot \vec{B}) \\ \vec{A} \cdot (c_1\vec{B}_1 + c_2\vec{B}_2) &= c_1(\vec{A} \cdot \vec{B}_1) + c_2(\vec{A} \cdot \vec{B}_2)\end{aligned}$$

Properties of the Sesquilinear Dot Product.

- a) (Positivity) If $\vec{A} \in \mathbb{C}^n$ then $\vec{A} \cdot \vec{A} \geq 0$, with equality if and only if $\vec{A} = \mathcal{O}$
- b) (Skew Symmetry) If $\vec{A}, \vec{B} \in \mathbb{C}^n$ then $\vec{A} \cdot \vec{B} = \overline{\vec{B} \cdot \vec{A}}$
- c) (Sesquilinearity) If $\vec{A}, \vec{B}, \vec{A}_1, \vec{A}_2, \vec{B}_1, \vec{B}_2 \in \mathbb{C}^n$ and $c_1, c_2 \in \mathbb{C}$ then

$$\begin{aligned}(c_1\vec{A}_1 + c_2\vec{A}_2) \cdot \vec{B} &= c_1(\vec{A}_1 \cdot \vec{B}) + c_2(\vec{A}_2 \cdot \vec{B}) \\ \vec{A} \cdot (c_1\vec{B}_1 + c_2\vec{B}_2) &= \overline{c_1}(\vec{A} \cdot \vec{B}_1) + \overline{c_2}(\vec{A} \cdot \vec{B}_2)\end{aligned}$$

Properties of the Cross Product

- a) (Bilinearity) If $\vec{A}, \vec{B}, \vec{A}_1, \vec{A}_2, \vec{B}_1, \vec{B}_2 \in \mathbb{R}^3$ and $c_1, c_2 \in \mathbb{R}$ then

$$\begin{aligned}(c_1\vec{A}_1 + c_2\vec{A}_2) \times \vec{B} &= c_1(\vec{A}_1 \times \vec{B}) + c_2(\vec{A}_2 \times \vec{B}) \\ \vec{A} \times (c_1\vec{B}_1 + c_2\vec{B}_2) &= c_1(\vec{A} \times \vec{B}_1) + c_2(\vec{A} \times \vec{B}_2)\end{aligned}$$

- b) (Antisymmetry) If $\vec{A}, \vec{B} \in \mathbb{R}^3$ then $\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$
- c) (Orthogonality) If $\vec{A}, \vec{B} \in \mathbb{R}^3$ then

$$\vec{A} \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\vec{A} \times \vec{B}) = 0$$

- d) (Lagrange Identity) If $\vec{A}, \vec{B} \in \mathbb{R}^3$ then $\|\vec{A} \times \vec{B}\|^2 = \|\vec{A}\|^2\|\vec{B}\|^2 - (\vec{A} \cdot \vec{B})^2$

- e) (Jacobi Identity) If $\vec{A}, \vec{B}, \vec{C} \in \mathbb{R}^3$ then

$$\vec{A} \times (\vec{B} \times \vec{C}) + \vec{B} \times (\vec{C} \times \vec{A}) + \vec{C} \times (\vec{A} \times \vec{B}) = 0$$

Axiomatic Definition of a Norm.

A function $\|\cdot\|$ on \mathbb{C}^n (or \mathbb{R}^n) that takes vectors to real numbers is called a *norm* provided the following three properties hold:

- N-I) (Positivity) For any $\vec{v} \in \mathbb{C}^n$ (or \mathbb{R}^n), we have $\|\vec{v}\| \in \mathbb{R}$, and in fact $\|\vec{v}\| \geq 0$ with equality if and only if $\vec{v} = \mathcal{O}$.
- N-II) (Homogeneity) If \vec{v} is a vector and c is a scalar, then $\|c\vec{v}\| = |c|\|\vec{v}\|$.
- N-III) (The Triangle Inequality) If \vec{v}_1, \vec{v}_2 are vectors, then $\|\vec{v}_1 + \vec{v}_2\| \leq \|\vec{v}_1\| + \|\vec{v}_2\|$.

Curvilinear Motion. Given a path $\vec{r}(t)$ in \mathbb{R}^n , we have

$$\begin{aligned} \text{Velocity: } \vec{v} &= \frac{d\vec{r}}{dt} & \text{Speed: } v &= \|\vec{v}\| & \text{Acceleration: } \vec{a}(t) &= \frac{d^2\vec{r}}{dt^2} \\ \text{Unit Tangent: } \vec{T} & & \text{Principle Normal: } \vec{N} & & & \end{aligned}$$

Acceleration in terms of its normal and tangential components:

$$\vec{a}(t) = \dot{v}\vec{T} + \kappa v^2 \vec{N}$$

Osculating plane at time t :

$$M\left(\vec{r}(t); \vec{T}(t), \vec{N}(t)\right) = \left\{ \vec{r}(t) + c_1\vec{T} + c_2\vec{N} \mid c_1, c_2 \in \mathbb{R} \right\}$$

Formula for curvature in an arbitrary parametrization:

$$\kappa(t) = \frac{\|v\vec{a} - \dot{v}\vec{v}\|}{v^3}$$

Special Formulas for Curvilinear Motion in \mathbb{R}^3

We have the *binormal*:

$$\vec{B} = \vec{T} \times \vec{N} \tag{1}$$

and the derivative equations

$$\begin{aligned} \frac{d\vec{T}}{ds} &= \kappa\vec{N} \\ \frac{d\vec{N}}{ds} &= -\kappa\vec{T} + \tau\vec{B} \\ \frac{d\vec{B}}{ds} &= -\tau\vec{N} \end{aligned}$$

We have the κ, τ equations in the arclength parametrization:

$$\begin{aligned} \kappa &= \left\| \vec{T} \times \frac{d\vec{T}}{ds} \right\| \\ \tau &= \kappa^{-2} \vec{T} \cdot \left(\frac{d\vec{T}}{ds} \times \frac{d^2\vec{T}}{ds^2} \right) \end{aligned}$$

and the κ, τ equations in an arbitrary parametrization:

$$\begin{aligned} \kappa &= \frac{\|\vec{v} \times \vec{a}\|}{v^3} \\ \tau &= \frac{\dot{\vec{r}} \cdot (\ddot{\vec{r}} \times \ddot{\vec{r}})}{\|\dot{\vec{r}} \times \ddot{\vec{r}}\|^2} \end{aligned}$$

Scratch

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