## Multiple Integral: Change of Variable

Say we have a multiple integral

$$
\begin{equation*}
K:=\iint_{\mathbb{R}^{2}} \frac{1}{\left[1+(x+2 y-1)^{2}+(3 x+y+2)^{2}\right]^{2}} d x d y \tag{1}
\end{equation*}
$$

and would like to make the change of variable

$$
\begin{equation*}
u=x+2 y-1, \quad v=3 x+y++2 \tag{2}
\end{equation*}
$$

since that would clean-up the integrand. How is this done?
Here is the general rule for

$$
J:=\iint_{\mathcal{D}} h\left(v_{1}, v_{2}\right) d v_{1} d v_{2}
$$

under the change of variable $\vec{v}=F(\vec{u})$ where $F(\vec{u})=\binom{f_{1}(\vec{u})}{f_{2}(\vec{u})}$ is given by

$$
v_{1}=f_{1}\left(u_{1}, u_{2}\right) \quad v_{2}=f_{2}\left(u_{1}, u_{2}\right) .
$$

Note that here we have defined the old variables, $\left(v_{1}, v_{2}\right)$ in terms of the new variables, $\left(u_{1}, u_{2}\right)$, while in equations (1)-(2) we defined the new variables, $(u, v)$ in terms of the old ones, $(x, y)$. In practice, one uses whichever is more convenient.
To begin, compute the first derivative (or Jacobian) matrix:

$$
F^{\prime}(\vec{u}):=\left(\begin{array}{ll}
\frac{\partial f_{1}\left(u_{1}, u_{2}\right)}{} & \frac{\partial f_{1}\left(u_{1}, u_{2}\right)}{\partial u_{1}}  \tag{3}\\
\frac{\partial f_{2}\left(u_{1}, u_{2}\right)}{\partial u_{1}} & \frac{\partial f_{2}\left(u_{1}, u_{2}\right)}{\partial u_{1}}
\end{array}\right) .
$$

Then the rule is

$$
d v_{1} d v_{2}=\left|\operatorname{det} F^{\prime}(\vec{u})\right| d u_{1} d u_{2}
$$

so in the new variables

$$
J=\iint_{\mathcal{D}^{\prime}} h\left(f_{1}\left(u_{1}, u_{2}\right), f_{2}\left(u_{1}, u_{2}\right)\right) \mid \operatorname{det}\left(F^{\prime}(\vec{u}) \mid d u_{1} d u_{2}\right.
$$

where $\mathcal{D}^{\prime}$ is the region in the $u_{1} u_{2}$ plane corresponding to $\mathcal{D}$.
Example 1 Compute $\iint_{R^{2}} \frac{1}{\left(1+x^{2}+y^{2}\right)^{2}} d x d y$.
We change to polar coordinates $\binom{x}{y}=F(r, \theta)$ with the usual formulas

$$
x=r \cos \theta \quad y=r \sin \theta .
$$

Then, as in equation (3), the first derivative matrix is

$$
F^{\prime}(r, \theta)=\left(\begin{array}{ll}
\frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\
\frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta}
\end{array}\right)=\left(\begin{array}{rr}
\cos \theta & -r \sin \theta \\
\sin \theta & r \cos \theta
\end{array}\right) .
$$

Since $\operatorname{det} F^{\prime}(r, \theta)=r$ we have $d x d y=r d r d \theta$ so

$$
\begin{equation*}
\iint_{R^{2}} \frac{1}{\left(1+x^{2}+y^{2}\right)^{2}} d x d y=\int_{0}^{2 \pi}\left(\int_{0}^{\infty} \frac{1}{\left(1+r^{2}\right)^{2}} r d r\right) d \theta=2 \pi \int_{0}^{\infty} \frac{1}{\left(1+r^{2}\right)^{2}} r d r=\pi . \tag{4}
\end{equation*}
$$

Example 2 For the integral in equation (1)-(2) if we write $\binom{u}{v}=G(x, y)$ then the first derivative matrix is

$$
G^{\prime}(x, y)=\left(\begin{array}{cc}
\frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\
\frac{\partial v}{\partial x} & \frac{\partial v}{\partial y}
\end{array}\right)=\left(\begin{array}{ll}
1 & 2 \\
3 & 1
\end{array}\right) \quad \text { so } \quad d u d v=5 d x d y
$$

Therefore, using polar coordinates, from equation (4)

$$
\begin{equation*}
K=\iint_{\mathbb{R}^{2}} \frac{1}{\left[1+(x+2 y-1)^{2}+(3 x+y+2)^{2}\right]^{2}} d x d y=\iint_{\mathbb{R}^{2}} \frac{1}{\left(1+u^{2}+v^{2}\right)^{2}} \frac{d u d v}{5}=\frac{\pi}{5} . \tag{5}
\end{equation*}
$$

The identical procedure works in in higher dimensions. In $\mathbb{R}^{n}$ say we have a multiple integral

$$
J:=\int \cdots \int_{\mathcal{D}} h\left(v_{1}, \ldots, v_{n}\right) d v_{1} \cdots d v_{n}
$$

and want to make the change of variable $\vec{v}=F(\vec{u})$. As above, compute the first derivative matrix

$$
F^{\prime}(\vec{u})=\left(\begin{array}{ccc}
\frac{\partial f_{1}(\vec{u})}{\partial u_{1}} & \cdots & \frac{\partial f_{1}(\vec{u})}{\partial u_{n}} \\
\vdots & \ddots & \vdots \\
\frac{\partial f_{n}(\vec{u})}{\partial u_{1}} & \cdots & \frac{\partial f_{n}(\vec{u})}{\partial u_{n}}
\end{array}\right) .
$$

Then the element of "volume" becomes

$$
d v_{1} \cdots d v_{n}=\left|\operatorname{det} F^{\prime}(\vec{u})\right| d u_{1} \cdots d u_{n} .
$$

This is particularly simple if one makes a linear change of variable, $\vec{v}=A \vec{u}$ where $A$ is an invertible matrix whose elements are constants, so $F(\vec{u})=A \vec{u}$. Then $F^{\prime}(\vec{u})=A$ and we obtain

$$
\begin{equation*}
d v_{1} \cdots d v_{n}=|\operatorname{det} A| d u_{1} \cdots d u_{n} \tag{6}
\end{equation*}
$$

and the change of variable formula is simply

$$
J:=\int \cdots \int_{\mathcal{D}} h(\vec{v}) d v_{1} \cdots d v_{n}=\int \cdots \int_{\mathcal{D}^{\prime}} h(A \vec{u})|\operatorname{det} A| d u_{1} \cdots d u_{n} .
$$

Example 3 Compute $J=\iint_{R^{2}} \frac{1}{\left(1+2 x_{1}^{2}+6 x_{1} x_{2}+9 x_{2}^{2}\right)^{2}} d x_{1} d x_{2}$.
Solution Write $2 x_{1}^{2}+6 x_{1} x_{2}+9 x_{2}^{2}=\langle\mathbf{x}, A \mathbf{x}\rangle$, where $A=\left(\begin{array}{ll}2 & 3 \\ 3 & 9\end{array}\right)$. Idea: If $A$ were the identity matrix, this would be straightforward, just use polar coordinates as in equation (4). Diagonalizing $A$ is thus the essential step.
Since $A$ is symmetric, it is orthogonally similar to a diagonal matrix, $A=R D R^{*}$, where $D=\left(\begin{array}{cc}\lambda_{1} & 0 \\ 0 & \lambda_{2}\end{array}\right)$ has the eigenvalues of $A$ on its diagonal and $R$ is an orthogonal matrix.

$$
\langle\mathbf{x}, A \mathbf{x}\rangle=\left\langle\mathbf{x}, R D R^{*} \mathbf{x}\right\rangle=\left\langle R^{*} \mathbf{x}, D R^{*} \mathbf{x}\right\rangle .
$$

Make the change of variable $\mathbf{y}=R^{*} \mathbf{x}$. In the integral, since $|\operatorname{det} R|=1$, then, by (6),

$$
d y_{1} d y_{2}=\left|\operatorname{det} R^{*}\right| d x_{1} d x_{2}=d x_{1} d x_{2}
$$

we find

$$
J=\iint_{R^{2}} \frac{1}{\left(1+\lambda_{1} y_{1}^{2}+\lambda_{2} y_{2}^{2}\right)^{2}} d y_{1} d y_{2} .
$$

Because $A$ is positive definite (there is a simple test for $2 \times 2$ matrices), its eigenvalues are positive so we make the further change of variable $z_{j}=\sqrt{\lambda} y_{j}$. This gives

$$
\lambda_{1} y_{1}^{2}+\lambda_{2} y_{2}^{2}=z_{1}^{2}+z_{2}^{2} .
$$

and

$$
d z_{1} d z_{2}=\sqrt{\lambda_{1} \lambda_{2}} d y_{1} d y_{2}=\sqrt{\operatorname{det} A} d y_{1} d y_{2}=3 d y_{1} d y_{2} .
$$

Thus, as in equation (4),

$$
J=\frac{1}{3} \iint_{R^{2}} \frac{1}{\left(1+z_{1}^{2}+z_{2}^{2}\right)^{2}} d z_{1} d z_{2}=\frac{\pi}{3} .
$$

It is interesting that although we used the theory that we could orthogonally diagonalize $A$, we never needed to compute explicitly its eigenvalues or eigenvectors.
Alternate For this and other examples where $\langle\mathbf{x}, A \mathbf{x}\rangle$ with $A$ positive definite arise, it is often faster (and clearer) to use that $A$ has a positive definite square root, that is, there is a positive dedinite (symmetric) matrix $B$ with $A=B^{2}$. Then

$$
\langle\mathbf{x}, A \mathbf{x}\rangle=\left\langle\mathbf{x}, B^{2} \mathbf{x}\right\rangle=\langle B \mathbf{x}, B \mathbf{x}\rangle=\|B \mathbf{x}\|^{2},
$$

which suggests making the change of variables $\mathbf{y}=B \mathbf{x}$ to find

$$
\langle\mathbf{x}, A \mathbf{x}\rangle=\|\mathbf{y}\|^{2} .
$$

If we use this approach in the above integral, then $d y_{1} d y_{2}=|\operatorname{det} B| d x_{1} d x_{2}=\sqrt{|\operatorname{det} A|} d x_{1} d x_{2}$ so

$$
J=\frac{1}{\sqrt{|\operatorname{det} A|}} \iint_{R^{2}} \frac{1}{\left(1+\|\mathbf{y}\|^{2}\right)^{2}} d y_{1} d y_{2} .
$$

As before, we now use polar coordinates (equation (4)) to conclude

$$
J=\frac{1}{3} \int_{0}^{2 \pi}\left(\int_{0}^{\infty} \frac{1}{\left(1+r^{2}\right)^{2}} r d r\right) d \theta=\frac{\pi}{3} .
$$

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